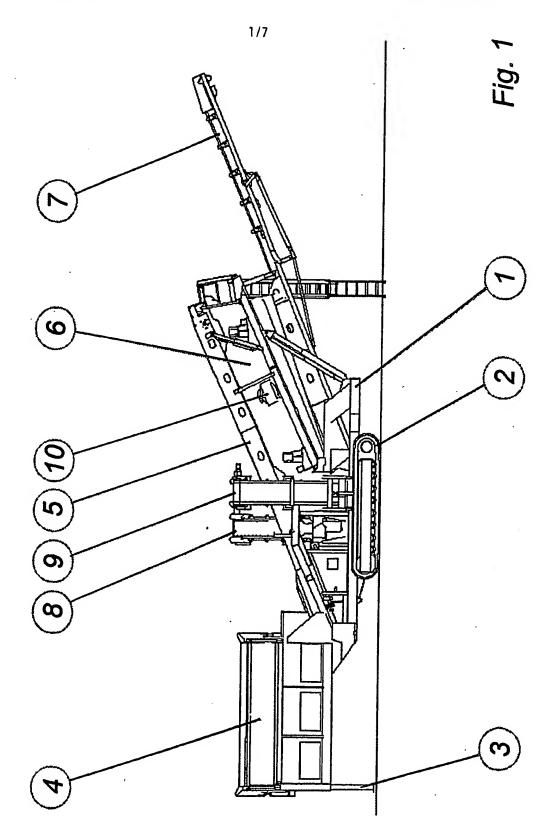
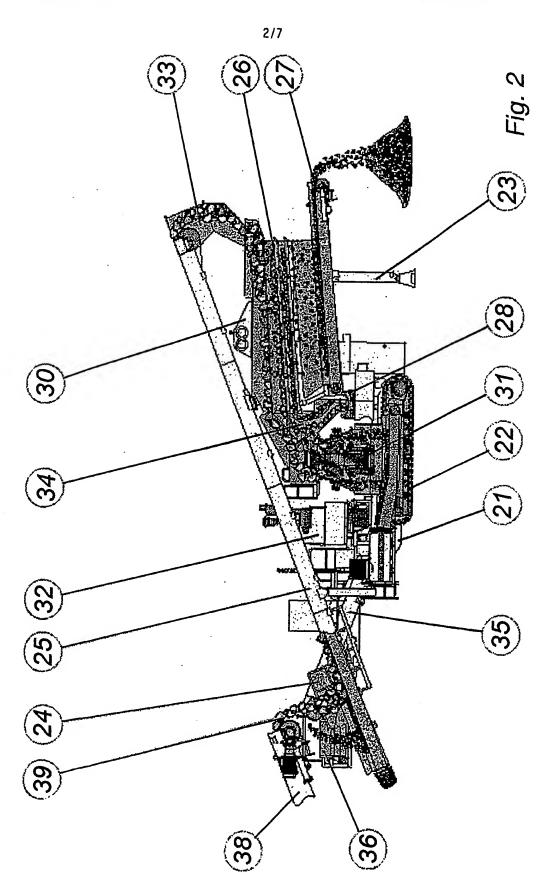
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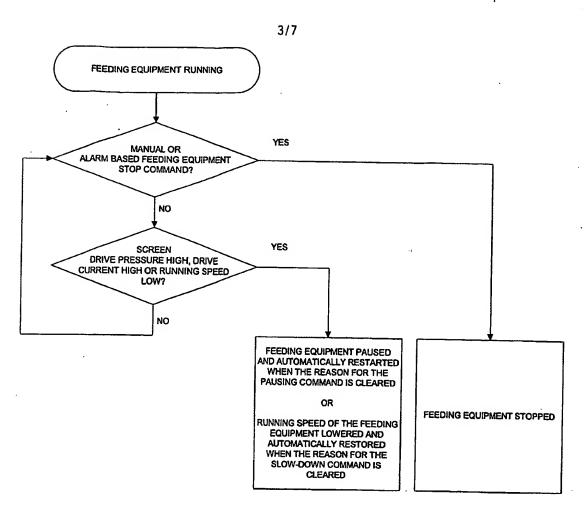
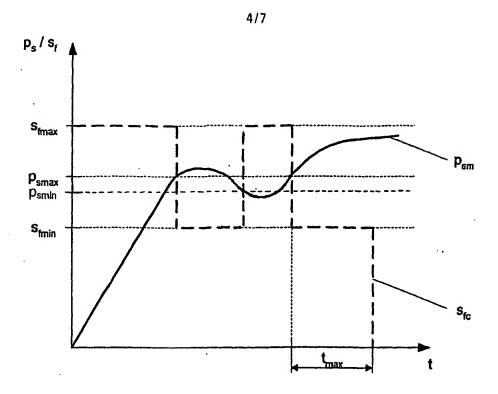


Fig. 3



t = time

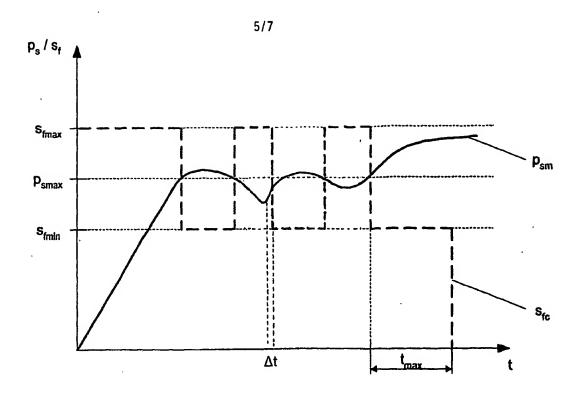
 $p_s$  = pressure of the screen drive system

s, = speed of the feeding equipment

 $p_{sm}$  = pressure of the screen drive system as measured (imaginary)

 $p_{smax}$  = maximum pressure of the screen drive system as set by the control system  $p_{smln}$  = minimum pressure of the screen drive system as set by the control system  $s_{fc}$  = speed of the feeding equipment as set by the control system to react to  $p_{sm}$   $s_{fmln}$  = minimum speed of the feeding equipment as set by the control system  $s_{fmax}$  = maximum speed of the feeding equipment as set by the control system  $t_{max}$  = maximum duration of  $p_{smax}$  overrun as set by the control system

Fig. 4a



t = time

p<sub>s</sub> = pressure of the screen drive system

s, = speed of the feeding equipment

 $p_{sm}$  = pressure of the screen drive system as measured (imaginary)

 $p_{smax}$  = maximum pressure of the screen drive system as set by the control system

 $(\Delta p_{sm}/\Delta t)_{max}$  = maximum speed of change of the pressure as set by the control system

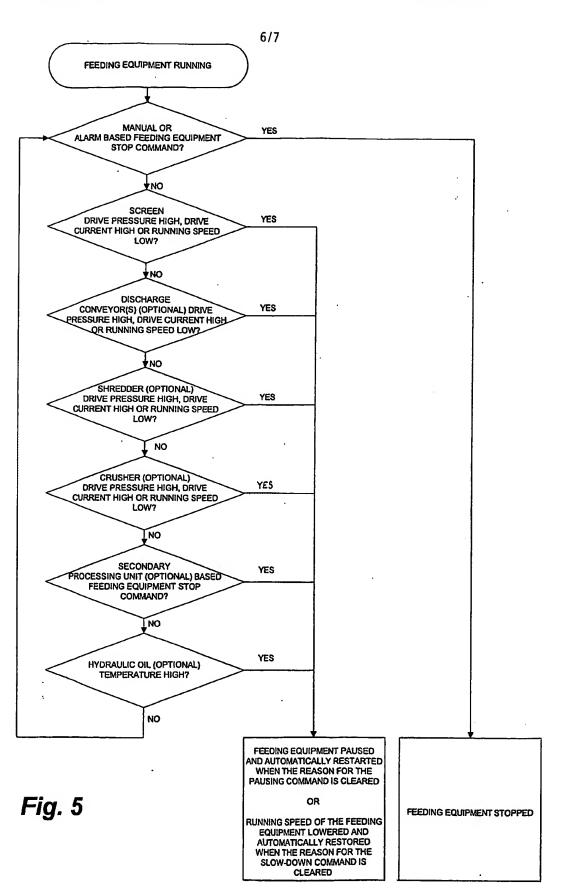
 $s_{fc}$  = speed of the feeding equipment as set by the control system to react to  $p_{sm}$ 

 $\mathbf{s}_{\text{fmin}}$  = minimum speed of the feeding equipment as set by the control system

 $\mathbf{s}_{\text{fmax}}$  = maximum speed of the feeding equipment as set by the control system

 $t_{max}$  = maximum duration of  $p_{smax}$  overrun as set by the control system

Fig. 4b



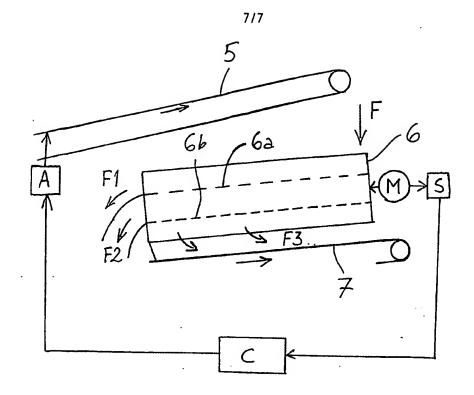


Fig. 6